

Class 2: Stochastic volatility models and heteroskedasticity

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PRESS RECORD

Learning outcomes

- ▶ Learn how to model changing variance in a time series
- ▶ Understand how to fit ARCH, GARCH and SVM models in JAGS
- ▶ Know how to compare and plot the output from these models

General principles of models for changing variance

- ▶ So far we have looked at models where the mean changes but the variance is constant:

$$y_t \sim N(\mu_t, \sigma^2)$$

- ▶ In this module we look at methods where instead:

$$y_t \sim N(\alpha, \sigma_t^2)$$

- ▶ These are:
 - ▶ Autoregressive Conditional Heteroskedasticity (ARCH)
 - ▶ Generalised Autoregressive Conditional Heteroskedasticity (GARCH)
 - ▶ Stochastic Volatility Models (SVM)
- ▶ They follow the same principles as ARIMA, but work on the standard deviations or variances instead of the mean
- ▶ forecast doesn't include any of these models so we'll use JAGS. There are other R packages to fit these models

Extension 1: ARCH

- ▶ An ARCH(1) Model has the form:

$$\sigma_t^2 = \gamma_1 + \gamma_2 \epsilon_{t-1}^2$$

where ϵ_t is the residual, just like an MA model

- ▶ Note that $\epsilon_t = y_t - \alpha$ so the above can be re-written as:

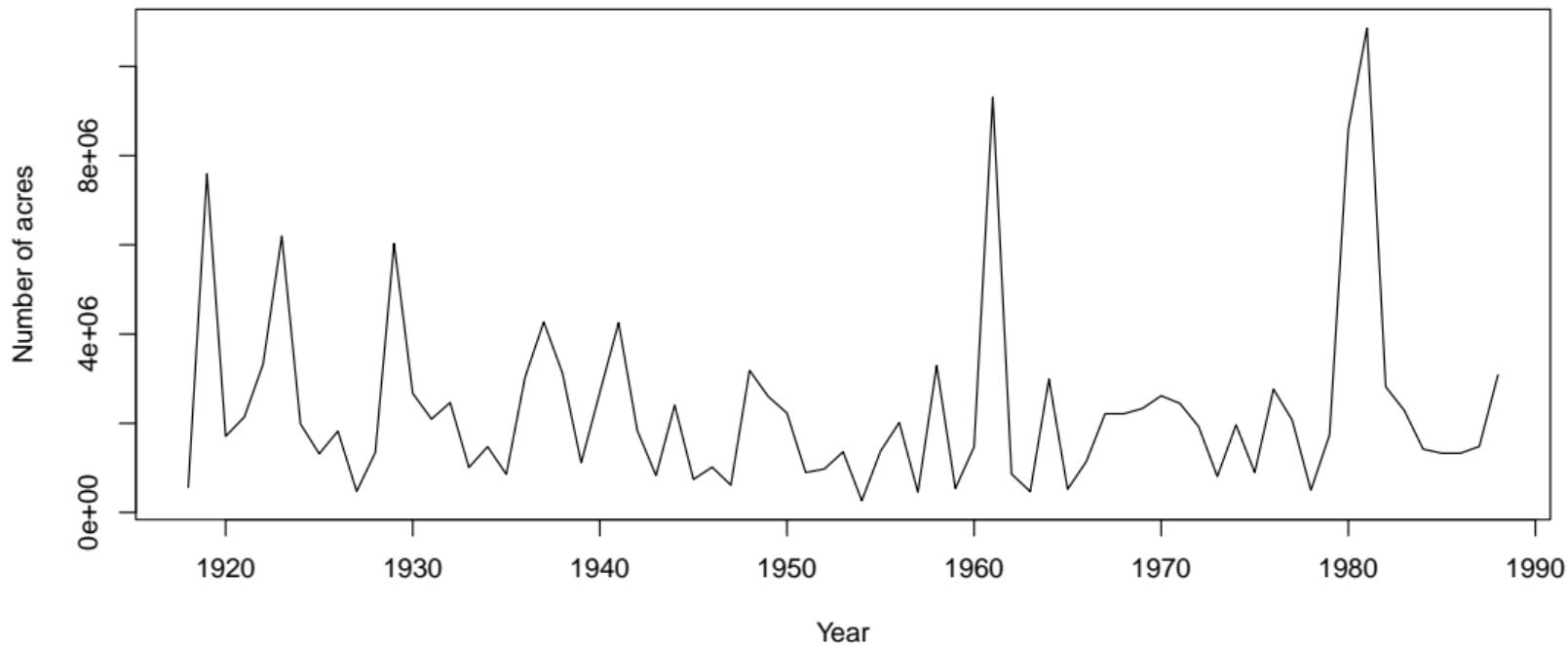
$$\sigma_t^2 = \gamma_1 + \gamma_2 (y_{t-1} - \alpha)^2$$

- ▶ The variance at time t thus depends on the previous value of the forecast error (more like an MA model than AR)
- ▶ The residual needs to be squared to keep the variance positive.
- ▶ The parameters γ_1 and γ_2 also need to be positive, and usually $\gamma_2 \sim U(0, 1)$

JAGS code for ARCH models

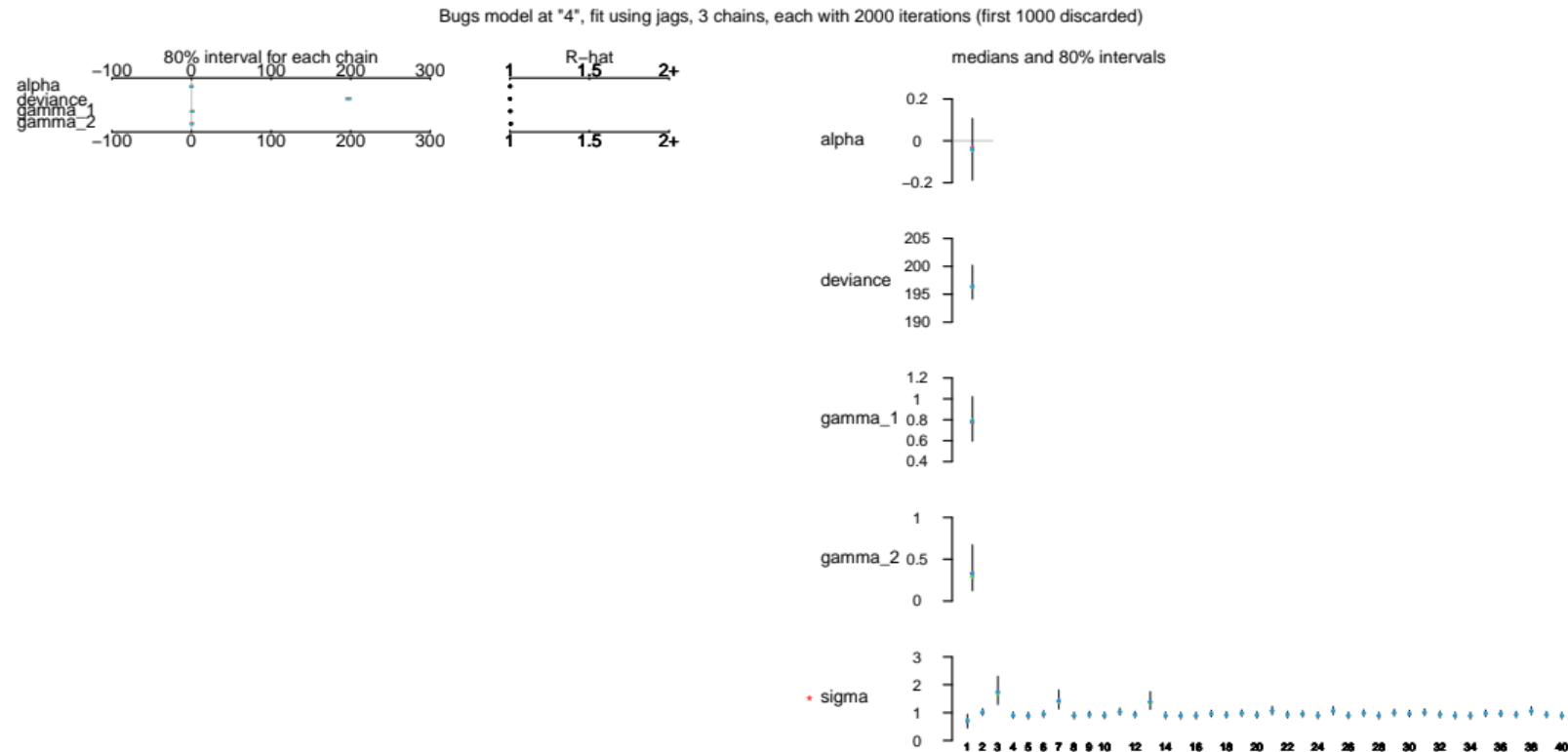
```
model_code = '  
model  
{  
    # Likelihood  
    for (t in 1:T) {  
        y[t] ~ dnorm(alpha, sigma[t]^~-2)  
    }  
    sigma[1] ~ dunif(0, 1)  
    for(t in 2:T) {  
        sigma[t] <- sqrt(gamma_1 + gamma_2 * pow(y[t-1] - alpha, 2))  
    }  
  
    # Priors  
    alpha ~ dnorm(0.0, 100^~-2)  
    gamma_1 ~ dunif(0, 100)  
    gamma_2 ~ dunif(0, 1)  
}
```

Reminder: forest fires data



ARCH(1) applied to forest fires data

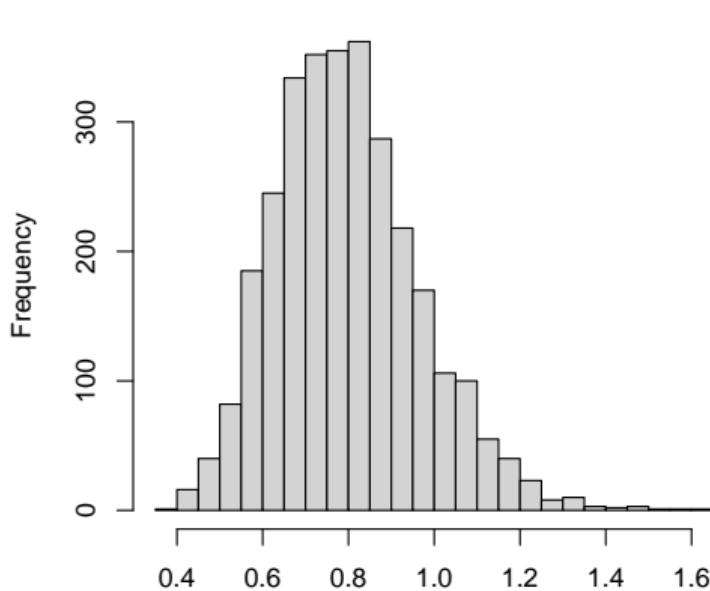
```
plot(ff_run)
```



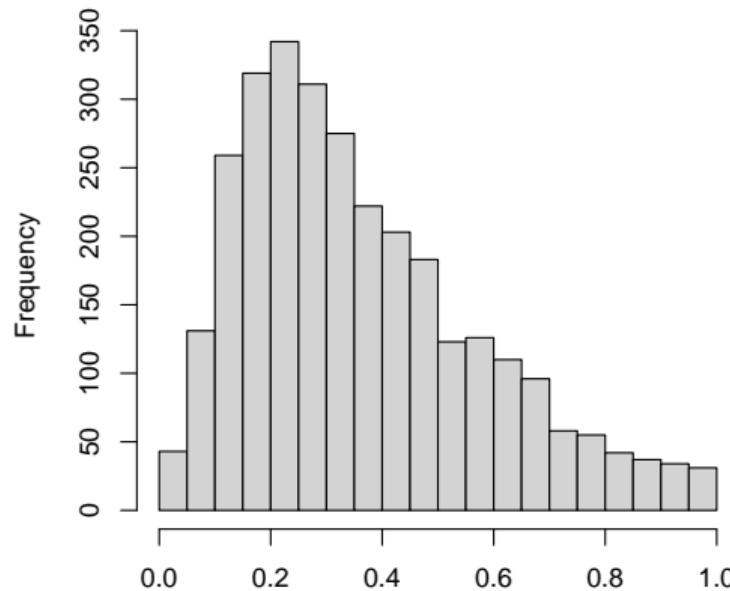
Plot the ARCH parameters

```
par(mfrow=c(1,2))  
hist(ff_run$BUGSoutput$sims.list$gamma_1, breaks=30)  
hist(ff_run$BUGSoutput$sims.list$gamma_2, breaks=30)
```

Histogram of ff_run\$BUGSoutput\$sims.list\$gamma_1 Histogram of ff_run\$BUGSoutput\$sims.list\$gamma_2

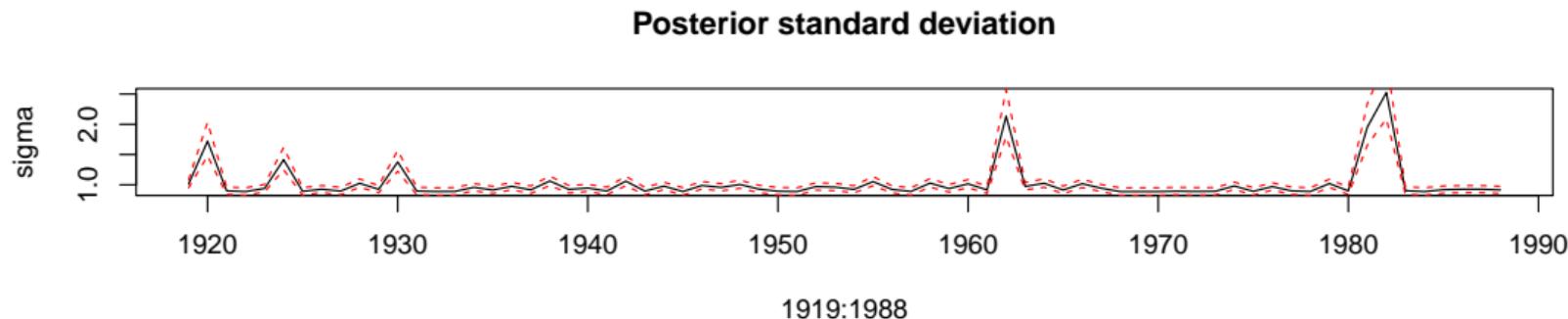
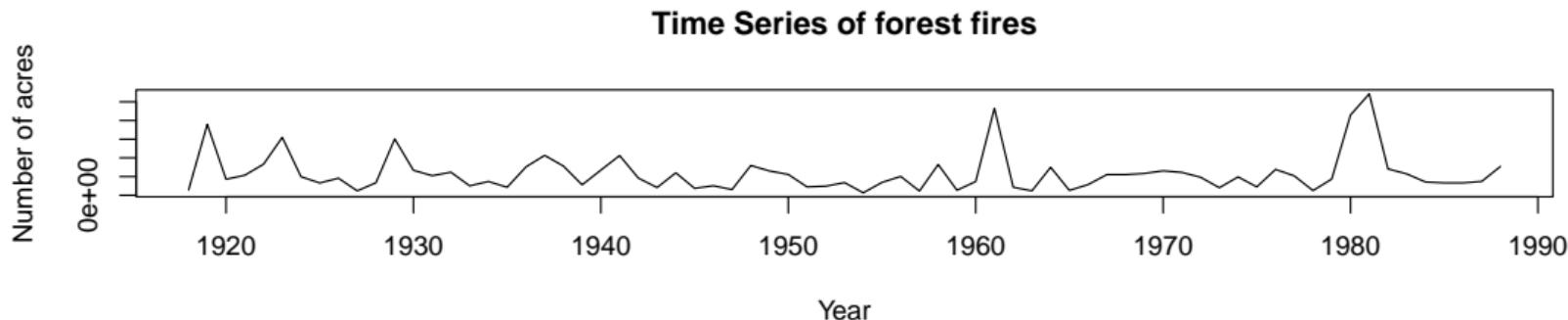


ff_run\$BUGSoutput\$sims.list\$gamma_1



ff_run\$BUGSoutput\$sims.list\$gamma_2

Plot the posterior standard deviations



From ARCH to GARCH

- ▶ The Generalised ARCH model works by simply adding the previous value of the variance, as well as the previous value of the observation
- ▶ The GARCH(1,1) model thus has:

$$\sigma_t^2 = \gamma_1 + \gamma_2(y_{t-1} - \alpha)^2 + \gamma_3\sigma_{t-1}^2$$

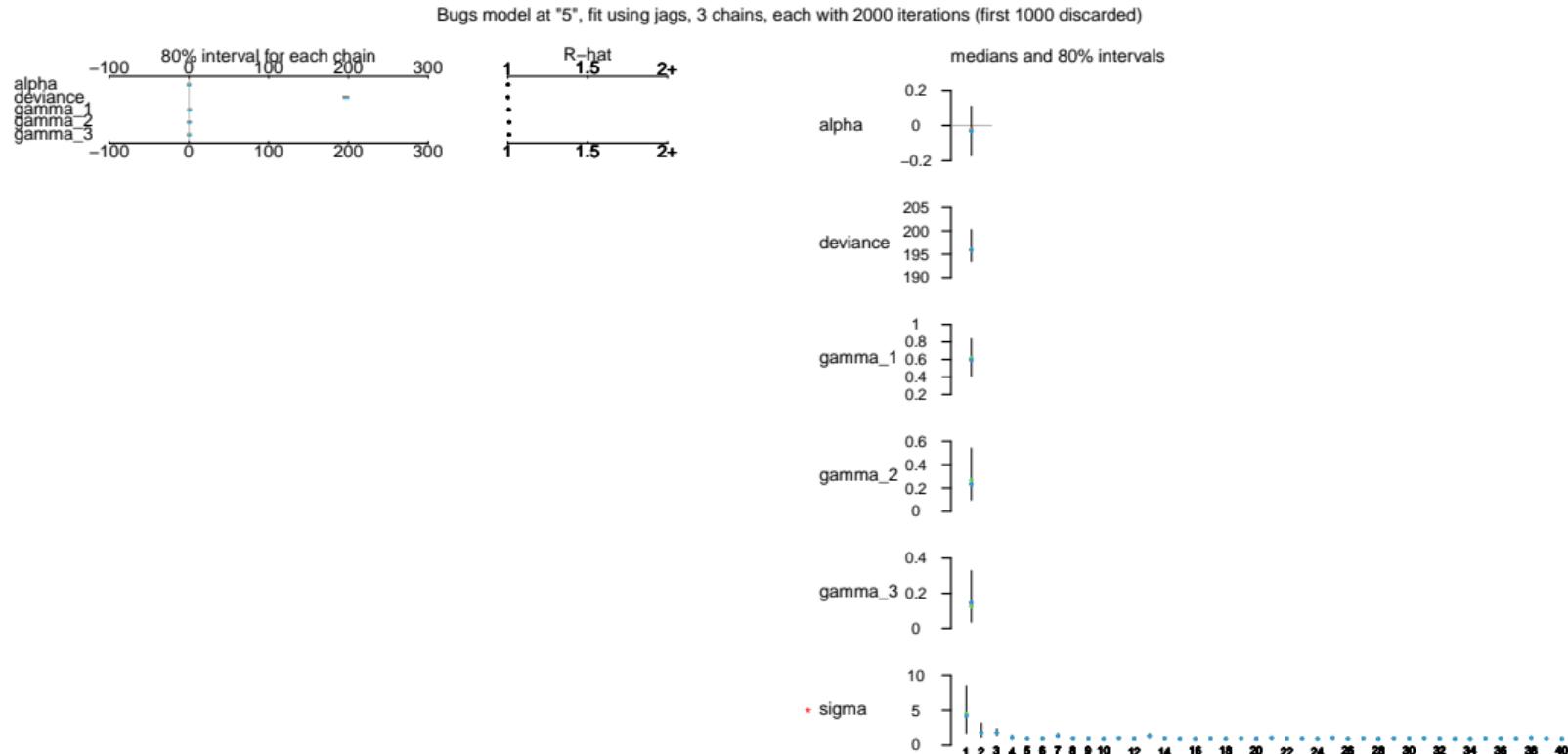
- ▶ There are, as always, complicated restrictions on the parameters, though like the stationarity conditions in ARIMA models we can relax this assumption and see if the data support it
- ▶ It's conceptually easy to extend to general GARCH(p,q) models which add in extra previous lags

Example of using the GARCH(1,1) model

```
model_code = '
model
{
  # Likelihood
  for (t in 1:T) {
    y[t] ~ dnorm(alpha, sigma[t]^~-2)
  }
  sigma[1] ~ dunif(0,10)
  for(t in 2:T) {
    sigma[t] <- sqrt(gamma_1 + gamma_2 * pow(y[t-1] - alpha, 2)
                      + gamma_3 * pow(sigma[t-1], 2))
  }
  # Priors
  alpha ~ dnorm(0, 10^~-2)
  gamma_1 ~ dunif(0, 10)
  gamma_2 ~ dunif(0, 1)
  gamma_3 ~ dunif(0, 1)
}
```

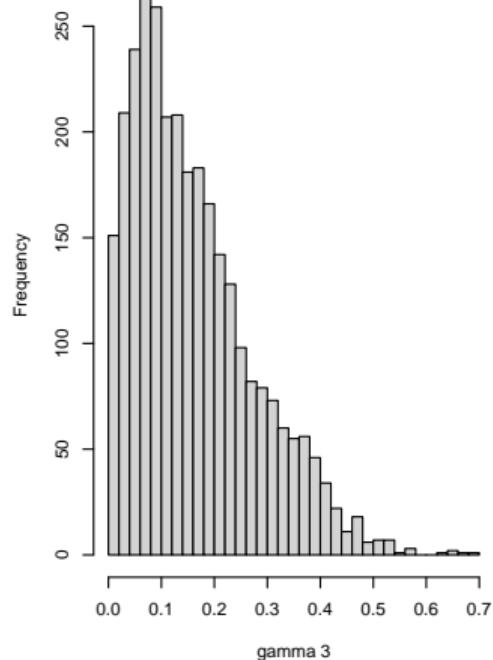
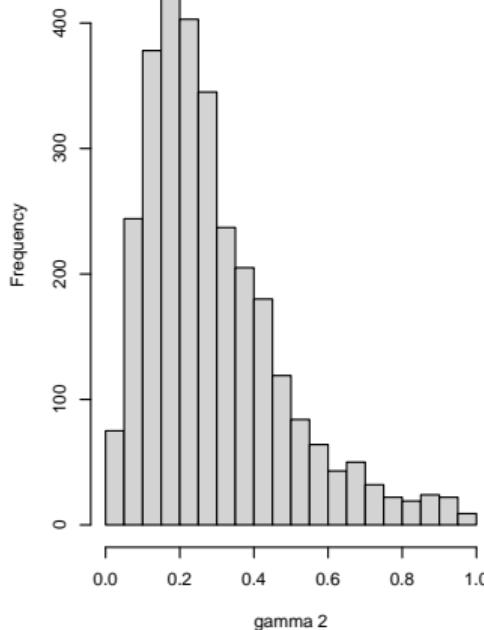
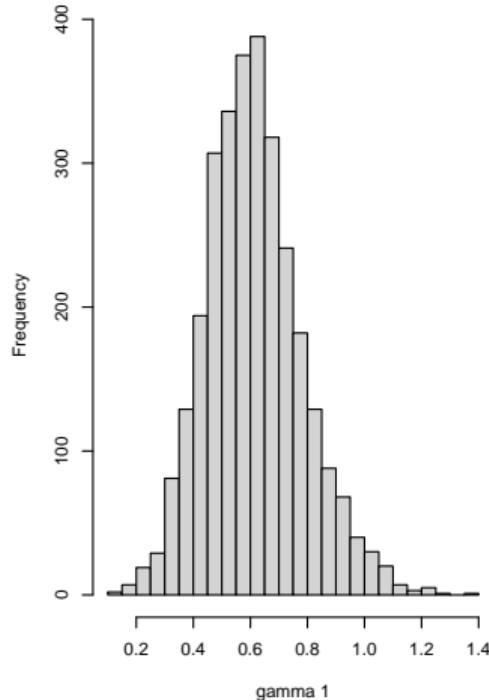
Using the forest fire data again

```
plot(ff_run_2)
```

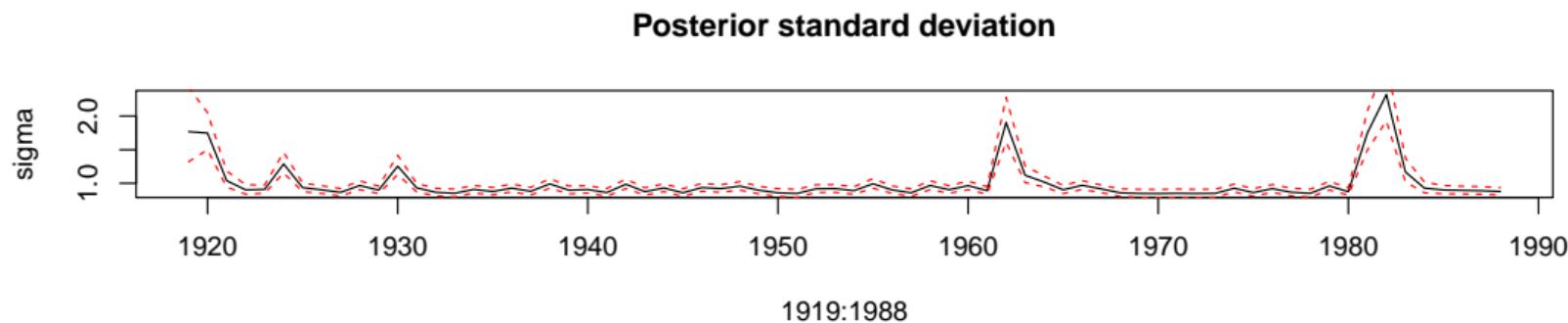
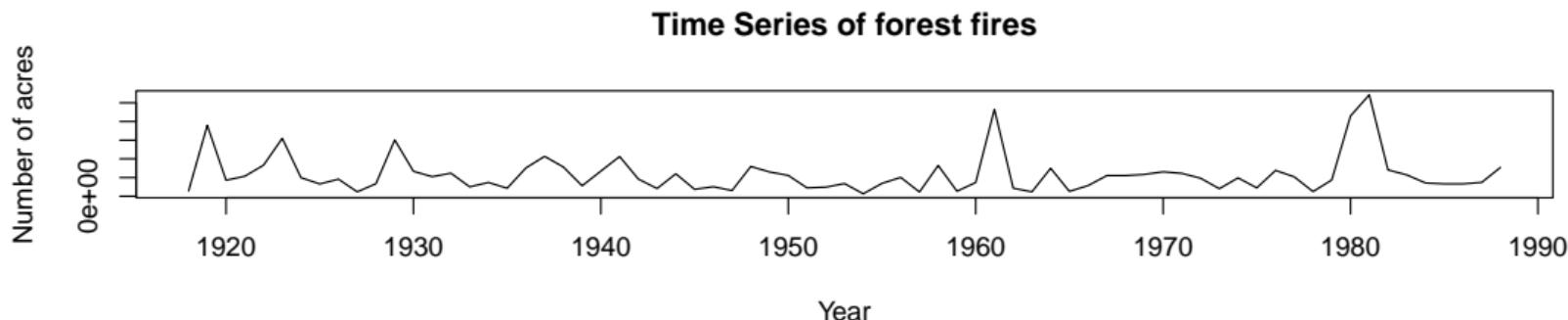


Looking at the GARCH parameters

histogram of ff_run_2\$BUGSoutput\$sims.list\$gamrhistogram of ff_run_2\$BUGSoutput\$sims.list\$gamrhistogram of ff_run_2\$BUGSoutput\$sims.list\$gamr



Posterior standard deviations over time



Compare with DIC

```
with(r_1, print(c(DIC, pD)))
```

```
## [1] 200.042129 3.187216
```

```
with(r_2, print(c(DIC, pD)))
```

```
## [1] 200.274240 3.817745
```

- ▶ Suggests not much difference between the models

Stochastic Volatility Modelling

- ▶ Both ARCH and GARCH propose a deterministic relationship for the current variance parameter
- ▶ By contrast a Stochastic Volatility Model (SVM) models the variance as its own *stochastic process*
- ▶ SVMs, ARCH and GARCH are all closely linked if you go into the bowels of the theory
- ▶ The general model structure is often written as:

$$y_t \sim N(\alpha, \exp(h_t))$$

$$h_t \sim N(\mu + \phi h_{t-1}, \sigma^2)$$

- ▶ You can think of an SVM being like a GLM but with a log link on the variance parameter

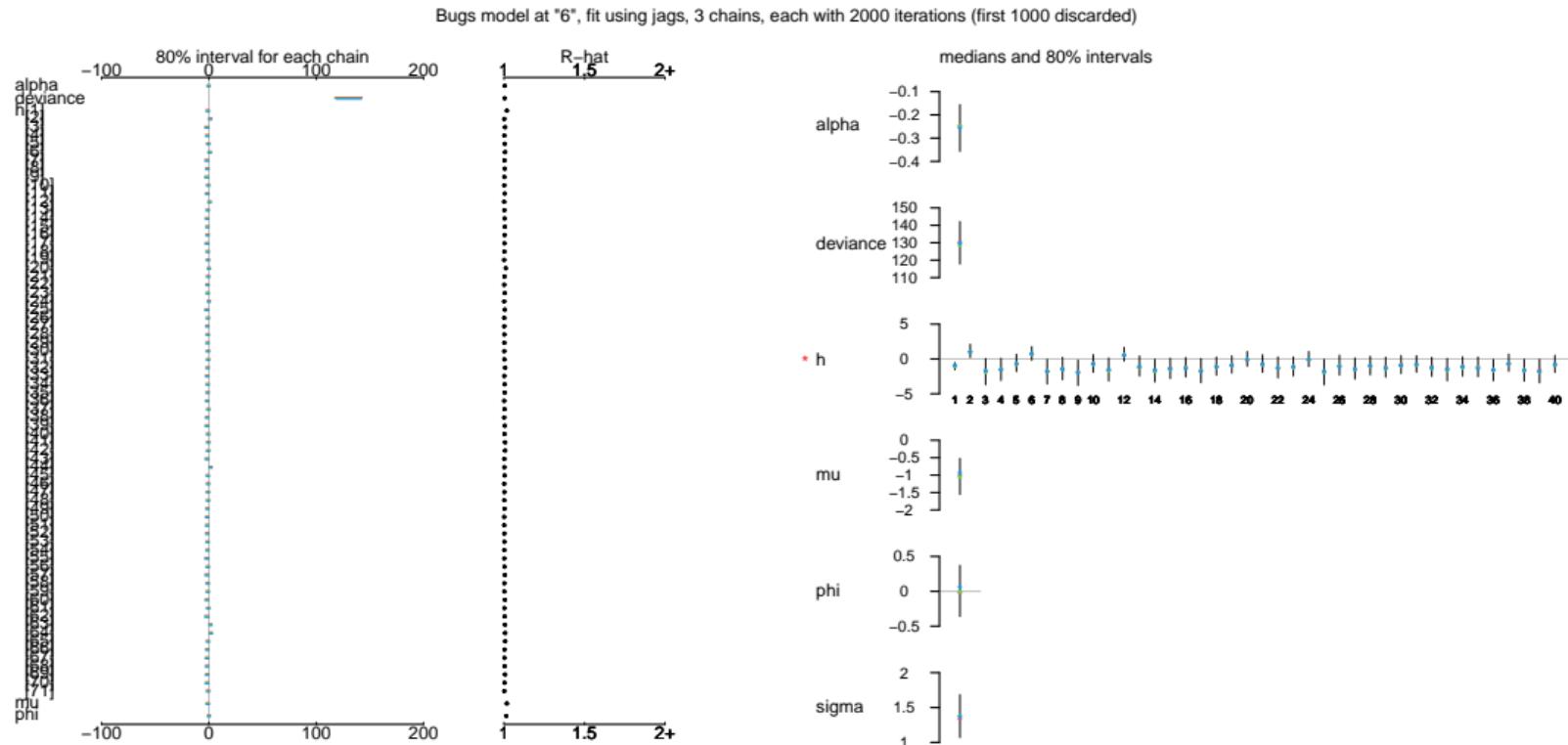
JAGS code for the SVM model

```
model_code = '
model
{
  # Likelihood
  for (t in 1:T) {
    y[t] ~ dnorm(alpha, sigma_h[t]^~-2)
    sigma_h[t] <- sqrt(exp(h[t]))
  }
  h[1] <- mu
  for(t in 2:T) {
    h[t] ~ dnorm(mu + phi * h[t-1], sigma^~-2)
  }

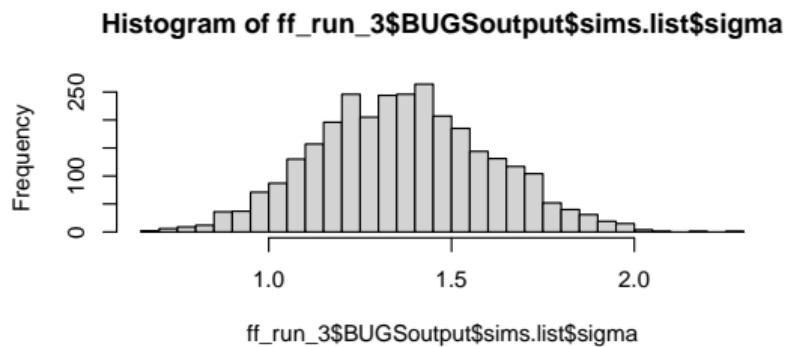
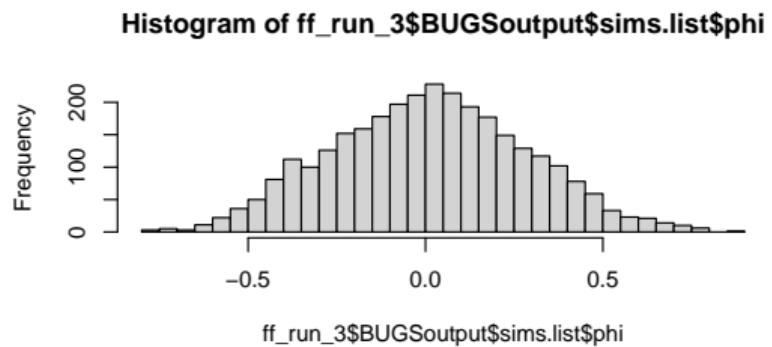
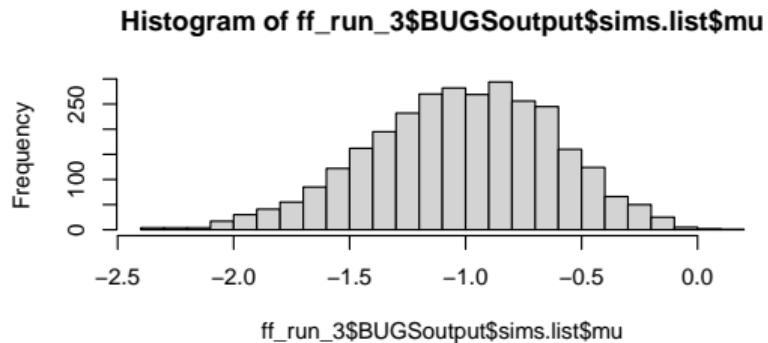
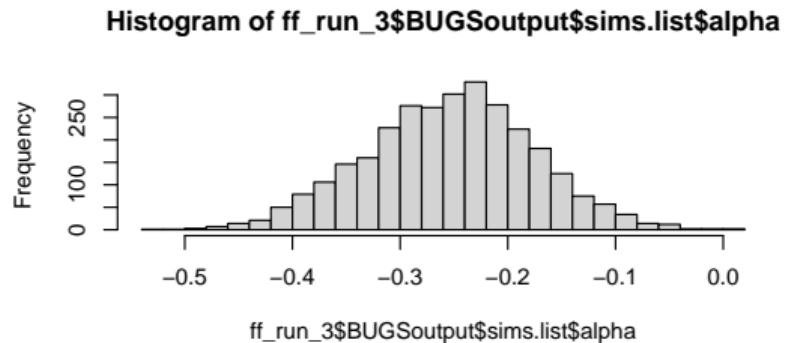
  # Priors
  alpha ~ dnorm(0, 100^~-2)
  mu ~ dnorm(0, 100^~-2)
  phi ~ dunif(-1, 1)
  sigma ~ dunif(0,100)
}
```

Example of SVMs and comparison of DIC

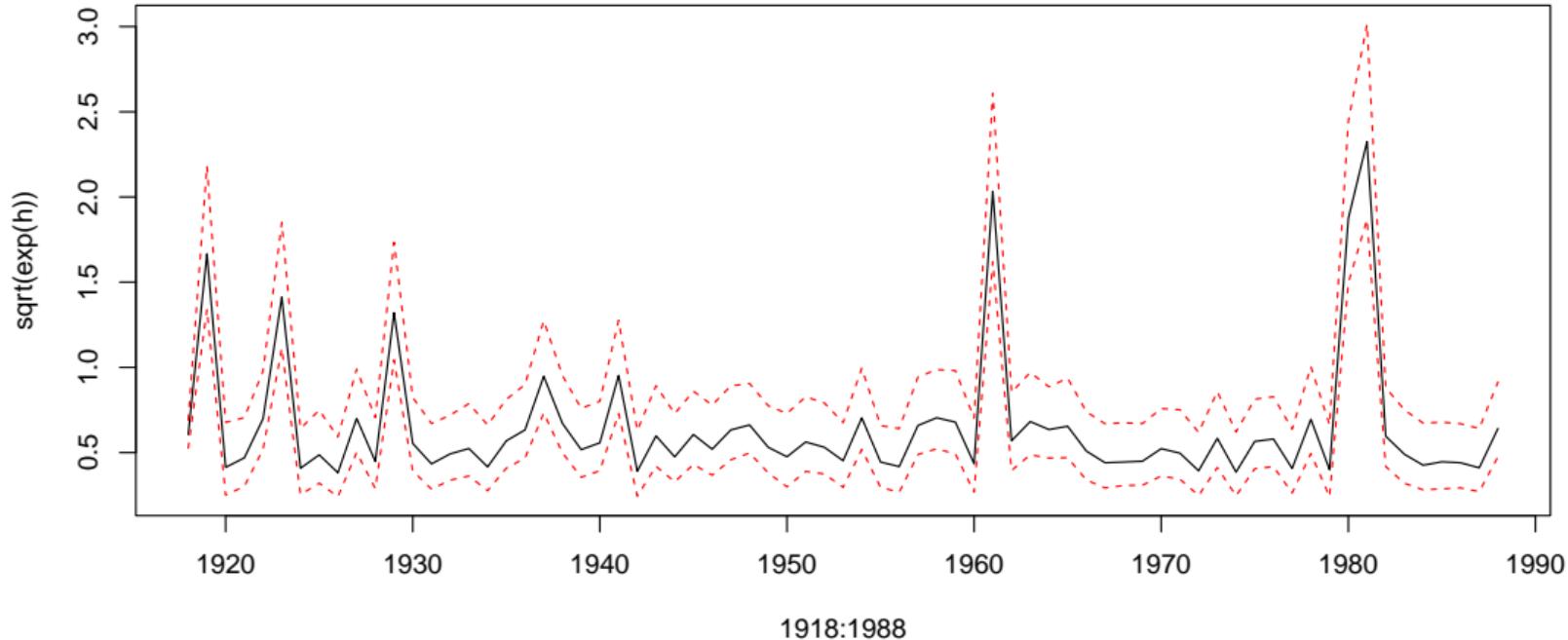
plot(ff_run_3)



Look at all the parameters



Plot of $\sqrt{\exp(h)}$



Comparison with previous models

```
with(r_1, print(c(DIC, pD)))  
## [1] 200.042129  3.187216  
with(r_2, print(c(DIC, pD)))  
## [1] 200.274240  3.817745  
with(r_3, print(c(DIC, pD)))  
## [1] 176.22957  46.40131
```

Much better fit, despite many extra parameters due to h !

Summary

- ▶ We know that ARCH extends the ARIMA idea into the variance using the previous values of the series
- ▶ We know that GARCH extends ARCH with previous values of the variance too
- ▶ We know that SVMs give the variance its own stochastic process
- ▶ We can combine these new models with all the techniques we have previously learnt